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| **HAZARDOUS AREA MONITORING FOR**  **INDUSTRIAL PLANTS POWERED BY IOT**      **SUBMITTED BY**      **AP LAKSHANA**                    **BACHELOR OF ENGINEERING IN ELECTRONICS**  **AND COMMUNICATION ENGINEERING**        **ASSIGNMENT-04** |

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| #include <WiFi.h>//library for wifi  #include <PubSubClient.h>//library for MQtt  #define ECHO\_GPIO 12  #define TRIGGER\_GPIO 13  #define MAX\_DISTANCE\_CM 100 // Maximum of 5 meters  #include "Ultrasonic.h"    Ultrasonic ultrasonic(13, 12); int distance;  void callback(char\* subscribetopic, byte\* payload, unsigned  int payloadLength);    //-------credentials of IBM Accounts------  #define ORG "dv1snq"//IBM ORGANITION ID  #define DEVICE\_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform  #define DEVICE\_ID "12345"//Device ID mentioned in ibm watson IOT Platform  #define TOKEN "45682367915" //Token String data3; float h, t;      //-------- Customise the above values --------  char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING |

**Question:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send “alert” to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud.

**Solution:**

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| char authMethod[] = "use-token-auth";// authentication method char token[] = TOKEN;  char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;//client id    // -  WiFiClient wifiClient; // creating the instance for wificlient  PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential  void setup()// configureing the ESP32  {  **Serial**.begin(115200); delay(10); **Serial**.println(); wificonnect(); mqttconnect();  } void loop()// Recursive  Function  { distance = ultrasonic.read(CM); if(distance < 100){  **Serial**.print("Distance in CM: ");  **Serial**.println(distance); PublishData(distance); delay(1000); if (!client.loop()) { mqttconnect();  }  } delay(1000);    }  /\*.....................................retrieving to Cloud.  ............................. \*/  void PublishData(float temp) { mqttconnect();//function call for connecting to ibm  /\* creating the String in in form JSon to update the data to ibm cloud  \*/  String payload = "{\"Alert Distance:\":"; |

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| payload += temp; payload  += "}";      **Serial**.print("Sending payload: ");  **Serial**.println(payload);      if (client.publish(publishTopic, (char\*) payload.c\_str())) {  **Serial**.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed  } else {  **Serial**.println("Publish failed"); }    } void mqttconnect() { if  (!client.connected()) {  **Serial**.print("Reconnecting client to "); **Serial**.println(server); while (!!!client.connect(clientId, authMethod, token)) { **Serial**.print("."); delay(500);  } initManagedDevice();  **Serial**.println();  } } void wificonnect() //function defination for wificonnect {  **Serial**.println();  **Serial**.print("Connecting to ");    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection while (WiFi.status() != WL\_CONNECTED) { delay(500); **Serial**.print("."); }  **Serial**.println("");  **Serial**.println("WiFi connected");  **Serial**.println("IP address: ");  **Serial**.println(WiFi.localIP());  } |

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| void initManagedDevice() { if  (client.subscribe(subscribetopic)) {  **Serial**.println((subscribetopic));  **Serial**.println("subscribe to cmd OK");  } else {  **Serial**.println("subscribe to cmd  FAILED"); } } void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength) {    **Serial**.print("callback invoked for topic: "); **Serial**.println(subscribetopic); for (int i = 0; i < payloadLength; i++) { //Serial.print((char)payload[i]); data3 += (char)payload[i];  }  **Serial**.println("data: "+ data3); if(data3=="lighton") {  **Serial**.println(data3);  } else  {  **Serial**.println(data3);  } data3="";  }      **Wokwi link:**  **https://wokwi.com/projects/346659959540286034** |

